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NRL Safety Inspection Checklist 15# Internal Inspection

Organization		Inspector Final PASS Time		
				Pit #
Type of Controller				
General Inspection		Pneumatic System		
\Box Name of Robot on exterior in $\frac{1}{2}$ letters min.		Verify that system is completely depressurized		
Appearance is acceptable		LPA or CO2 disposable cartridges are allowed		
Safety covers installed and secure		Tanks have pressure-reliefs or blowout plugs		
Safety restraints installed and secure		Tanks are mounted securely within chassis		
No disallowed materials		Tanks are properly rated and tested		
Restricted material complies with rules		Max Capacity limit (8 cu.ft.) at 70 degrees F		
		Mark max f	fill pressure on ALL tanks	
Electrical Inspection		Low pressure shut-off valves meet requirements		
Drive switch mechanically shuts off batteries		Pressure regulator mounted directly to tank		
Weapon switch mechanically shuts off batteries		Pressure regulator has lock-down mechanism		
Master switches are 2-	position and enclosed	Mark max pressure on regulators		
Master switch access requires no parts removal		LPA 150psi max at 70 degrees F		
Access to all switches is outside weapon path		CO2 853psi max at 70 degrees F		
External light for each switch is visible		□ 150psi max on low pressure side		
Legal Batteries NO Li-Poly!		Armor is required to secure any vessels		
Batteries are mounted securely within chassis		Pneumatic components are correctly rated		
Battery terminals/connections covered/insulated		Pneumatic components are mounted securely		
All wiring is properly installed and insulated		No damage to any pneumatic components		
Maximum voltage does not exceed limit (28V)		Pressure purge valves meet requirements		
Demored Weenene		Purge and	d shut-offs are outside weapons area	
Powered weapons		□ No heat source close to pneumatic components		
U weapons are not electrical/electromagnetic		Access for tank filling is safe and stable		
U Weapons do not use heat, fire or explosives		Refilling system approved		
□ weapons are non-rouir	ng			
U weapons/flywneels are securely attached		Additional	Itoms	
Deactivated weapons pose no nazard to people				
Less than 20 minutes to charge modular weapon		□ IVIUIUDUL II	willing and a specific requirements	
Large Springs			iy/sound system can be dedclivated	
Deactivated enringe ha	ve less than 5 lbs force			
□ All springs are mounted	d securely			
Manual safety release design is approved				

FAIL: Items to be Fixed

Inspector Signature: _____

Team Representative:

Comments:



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15# Functional Inspection Checklist

Inspector:	Robot Name:	
Pass No Pass	Weight:	
Pneumatic System Verify that system is completely pressurized Tank pressures do not exceed sticker limits Regulated pressures do not exceed sticker limits Add colored tape to top and bottom or Robot Activation of Robot Move Robot to test box or arena Robot is in full fight-ready configuration Verify Robot is completely Deactivated Check that all Master switches are off Turn the Transmitter ON No Robot movement when transmitter is turned	 Move the Robot at high speed Turn transmitter OFF during motion Power to drive system stops when transmitter is shut off Powered Weapon Systems Testing Start EACH weapon system moving Weapons systems are reliably controlled Turn transmitter OFF while weapon is on Power to weapon system stops when transmitter is shut off Spinning parts come to a FULL stop within 30 seconds after transmitter is shut off 	
on Activate the Robot	Weapon will NOT cause damage to arena Deactivation of Pohot	
 Activate the Robot Activation requires no more than 1 person Person NOT in weapon path during activation Activation can be done within 45 seconds No panels/parts removal during Activation Activation Safety procedure is acceptable Motion System Fail-Safe Test	Deactivation of Robot Turn the transmitter ON Deactivate the Robot Deactivation requires no more than 1 person Person NOT in weapon path during Deactivation Critical Deactivation Less than 15 seconds Complete Deactivation LESS than 60 seconds No panels/parts removal during Deactivation	
 Move the Robot under control Robot motion control is continuous, not random Reliable control of the motion-producing parts Motion speed greater than 1 foot-per-second Move the Robot at high speed Turn transmitter OFF during motion 	Deactivation Safety procedure is acceptable	
FAIL: Items to be Fixed	<u>Comments:</u>	
Inspector Signature:		

Team Representative: _____



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